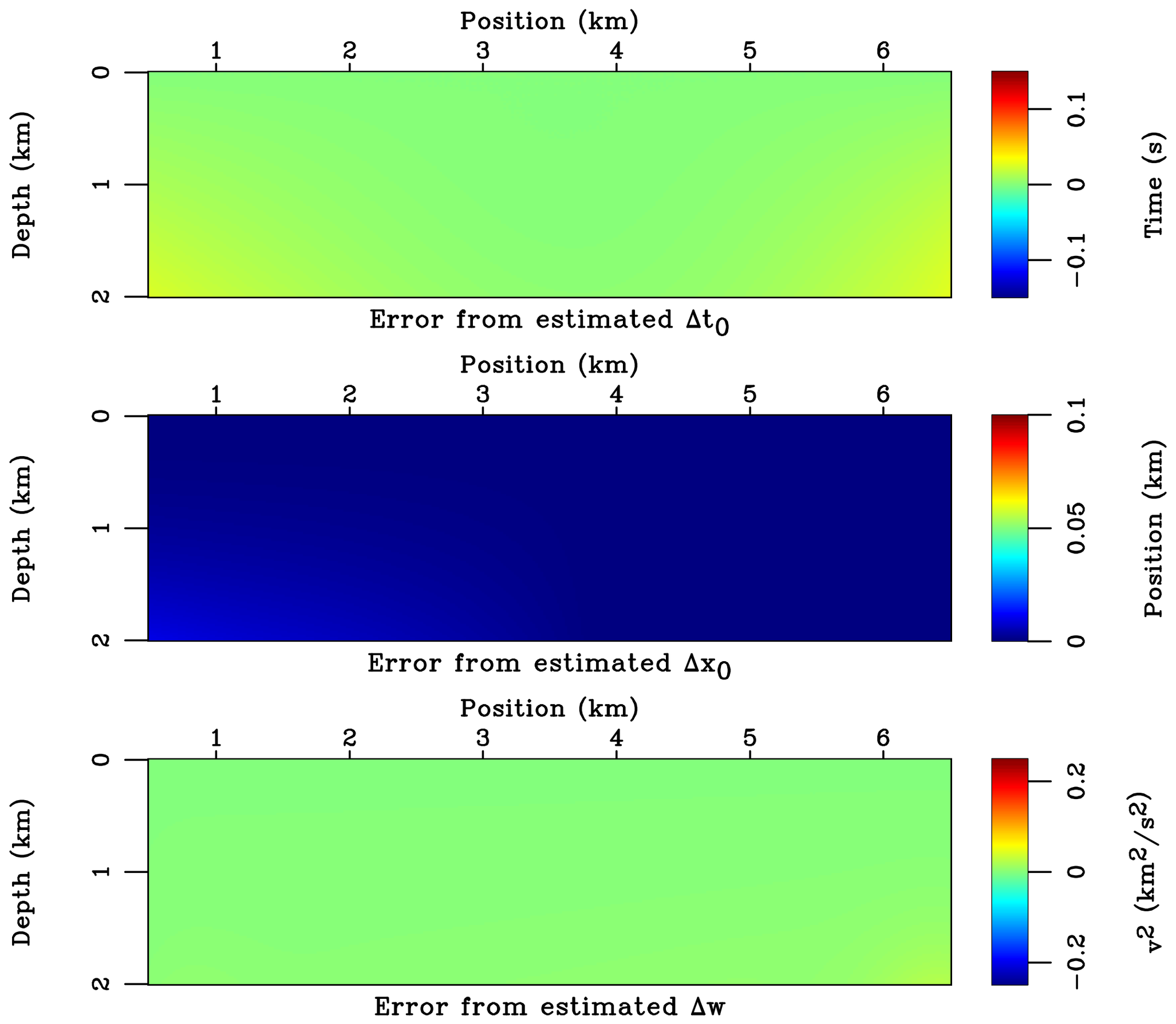
Position (km)
1
2
3
4
5
6
Depth (km)
0
1
2
Time (s)
0.1
0
−0.1
Error from estimated Δt_0
Position (km)
1
2
3
4
5
6
Depth (km)
0
1
2
Position (km)
0.1
0.05
0
Error from estimated Δx_0
Position (km)
1
2
3
4
5
6
Depth (km)
0
1
2
v^2 (km^2/s^2)
0.2
0
−0.2
Error from estimated Δw